

Optical Control Plane: Practical Implementation Strategies

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Control Plane Considerations

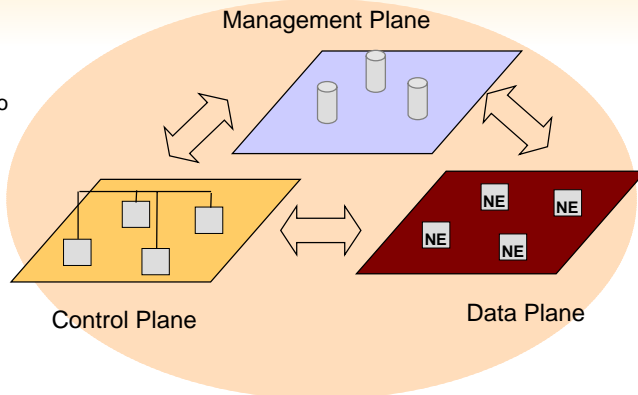
- Unified control plane (UCP) initiatives strive to lower costs and increase service potential
- The UCP is made possible by advances in network elements and standards
- Several UCP standards efforts and implementation models exist
 - ITU-T ASON
 - IETF GMPLS
 - OIF UNI/NNI
- Adopting a UCP has impacts on transport and management processes, and requires input and involvement of multiple organizations



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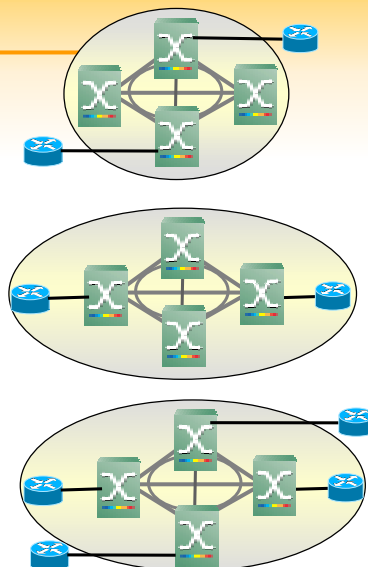
Managing the Transition

- Broad UCP adoption has multiple dependencies:
 - Standards progress and adoption
 - Ease of integration into existing networks
 - Predictability, control, reliability, security
- Organizational impacts must be minimized and controlled :
 - People
 - Process
 - Services

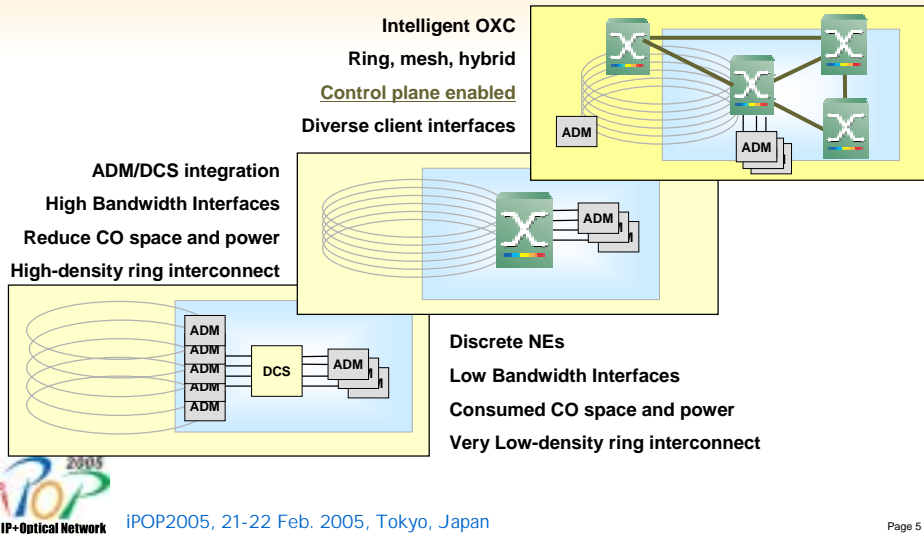


Implementation Models

- Overlay model
 - Two independent control planes
 - IP Domain
 - Optical domain
 - Router is client of optical domain
 - Optical topology invisible to routers
- Peer model
 - Single integrated control plane
 - Router and optical switches are peers
 - Optical topology is visible to routers
- Hybrid options exists
 - Combine benefits of both models

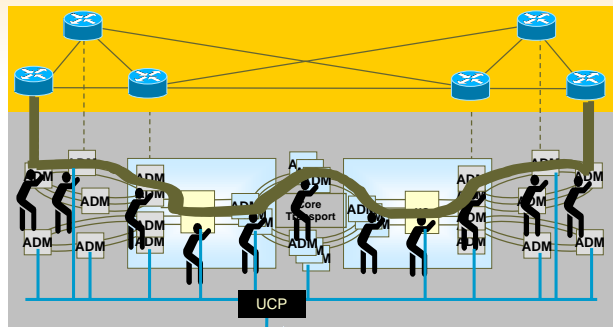


Network Element Trends: Consolidation and Intelligence



Unified Control Plane Benefits are Compelling. . .

- Rapid, flexible delivery of new services
 - Faster time to revenue
 - Improved customer satisfaction and appeal
 - Highly customizable, service-focused network
- Increased automation, standard based interop
 - Reduced OPEX
 - Reduced CAPEX
 - Optimization of transport capital investment



Control Plane Transition

Today

- Architecture:** Proprietary
- Control Plane:** No Control Plane, inventory, planning, provisioning via 3rd party tools and interfaces
- Inventory:** Offline inventory data-base, changes to network / services require manual input
- Path Selection:** Offline, manual activity, resource info provided by inventory data-base
- Path Placement:** via multiple manual local configuration activities or proprietary OSS



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Future

- Architecture:** ITU-T ASON or Peer Model
- Control Plane:** Embedded in distributed optical NEs, integrate with NMS and 3rd party tools
- Inventory:** UCP auto-discovers resources, synchronizes network with inventory data-base, changes auto-updated
- Path Selection:** UCP and/or NMS activity based on routing updates of current network resources and conditions
- Path Placement:** dynamic placement via standard signaling protocols

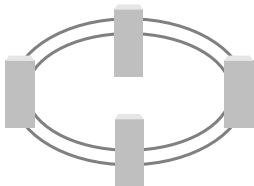


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Transport Plane Transition

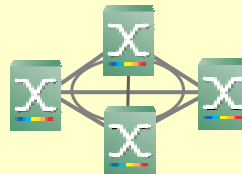
Today

- Ring-based protection schemes with dedicated protection
- No control plane
- Single, inefficient restoration option
- Limited service differentiation
- Limited Operations automation



Future

- Mix of Ring, Mesh and Hybrid Schemes with a variety of protection mechanisms
- Implements Optical Control Plane
- Multiple, efficient restoration options
- Highly differentiated services options
- Highly automated operations



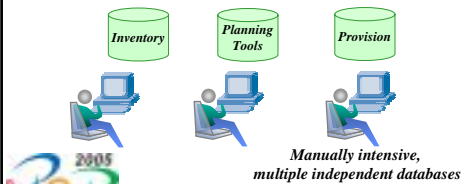
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Management Plane Transition

Today

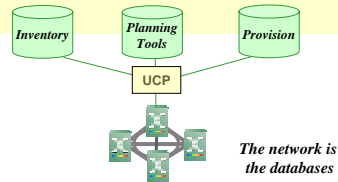
- FCAPS
- Wide variety of independent management and monitoring tools
- Data manually entered / maintained in offline data-bases: *information silos*
- Integration between management and monitoring tools, and between tools and OSS, achieved via a wide variety of standard and customized interfaces



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Future

- FCAPS
- Wide variety of independent management and monitoring tools integrated with network
- Data automatically gathered and maintained via control plane integration using TMF 814 CORBA: FCAPS + Connection Mgmt
- Integration between management and monitoring tools, and between tools and OSS, converges on standard interfaces



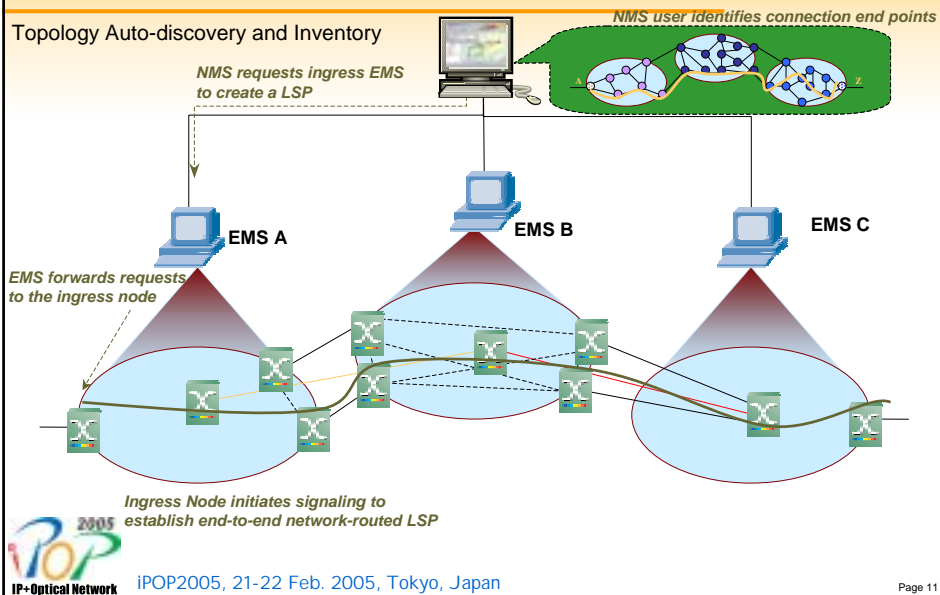
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Putting it All Together

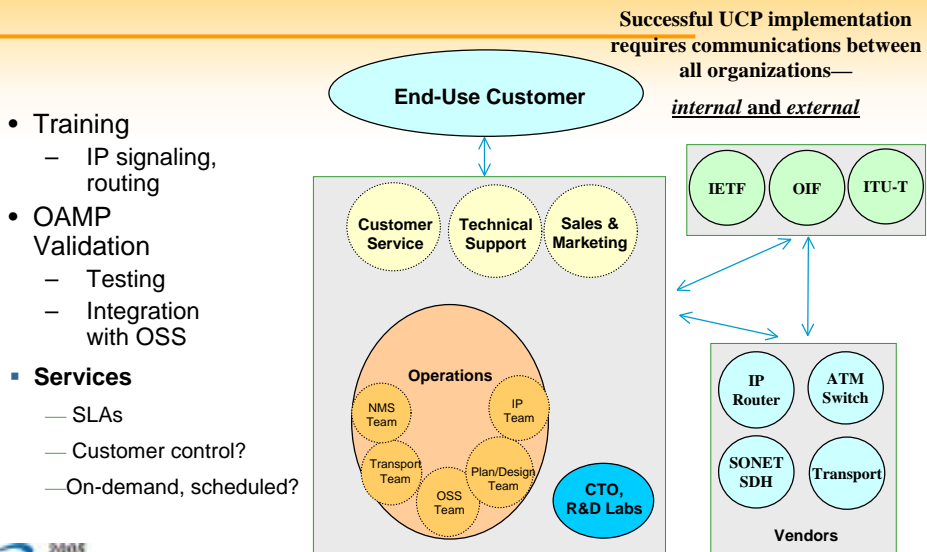
- Transport Plane
- Control Plane
- Management Plane



SPC Provisioning Example



Organizational Impacts

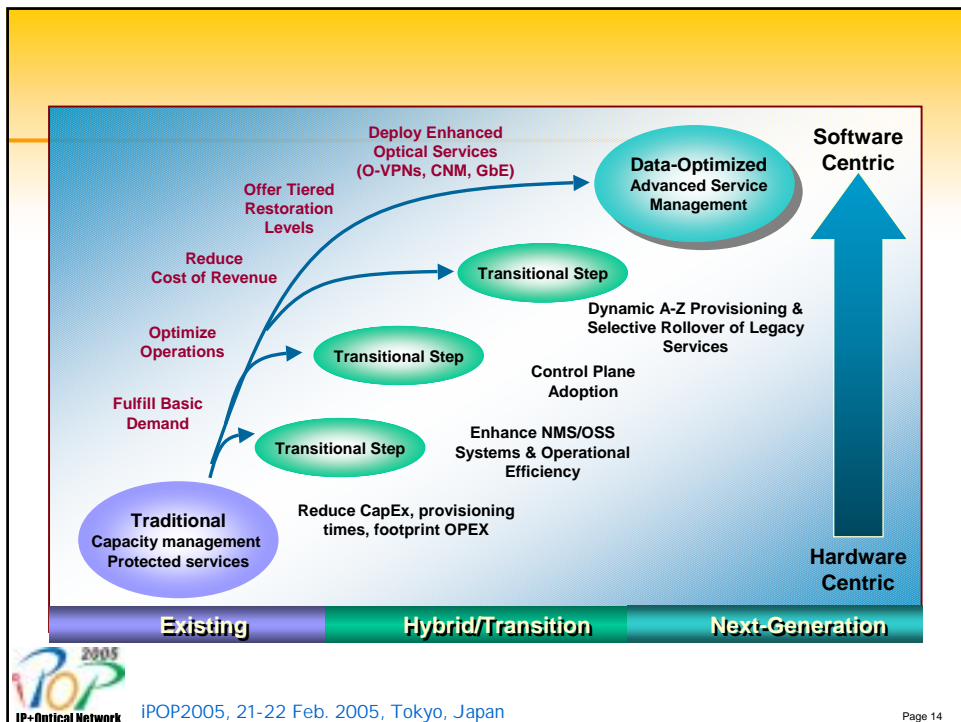


Service Differentiation

- Increase Market Appeal
 - Customization via a range of restoration, bandwidth, provisioning, and management options
- Reduced OPEX Costs
 - Automated service delivery and modification
- Increased Revenue Generation
 - Via innovative services and improved network utilization

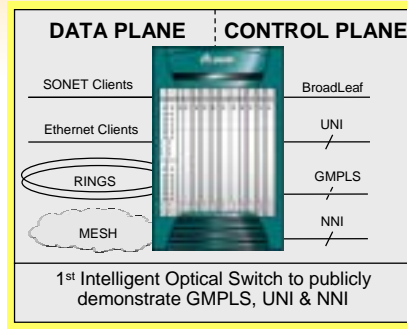
Service Characteristics	Broad Range of Options	Value
Bandwidth	STS-1/VC-3, OC-3/STM-1, OC-12/STM-4, OC-48/STM-16, OC-192/STM-64	BW Dependent
+ Service Selection	Protected Fixed Private Line, Unprotected Fixed Private Line, Flex Private Line, Optical VPN etc.	Selection Dependent
+ Provisioning Option	Basic, Rapid, Self Service, Dynamic, Policy, etc....	Option Dependent
+ Protection Scheme	Local Restoration, Mesh Restoration, Unrestored, Client Protection, Diversely Routed...	Scheme Dependent
+ Management Choice	Managed Service, Customer Network Management	Choice Dependent
+ Service Level Agreement	Tiered Optical SLA (based on uptime, delay, restoration)	Agreement Dependent


Highly Customized Service Offering
with
Flexible Market-Based Pricing



Sycamore Control Plane Highlights

- Supports multiple approaches
 - GMPLS, OIF UNI, OIF ENNI, BroadLeaf
- Long standing standards participation
 - Founding, Principal Member of OIF, '00
 - Interim UNI Test; Supercomm '01
 - GMPLS Signaling Test, NGN '02
 - UNI 1.0 / Interim NNI Test; OFC '03
 - MPLS over GMPLS Test, MPLS Conf. '03
 - OIF Worldwide Demo, Supercomm '04
 - Isocore IP/Optical Test, Supercomm '04
 - Isocore, October 2004
 - iPOP, February 2005



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Summary

- Optical control plane initiatives promise to lower costs, increase service potential
- Co-existence with existing OAM&P, traditional services
 - NMS and OSS
 - Ring and mesh
- The Unified Control Plane can be implemented gradually, practically
 - Transition involves communication with vendors, standards bodies, and internal organizations

